



#### **BUSITEMA UNIVERSITY**

# FACULTY OF ENGINEERING DEPARTMENT OF COMPUTER ENGINEERING

## FINAL YEAR PROJECT REPORT

TITLED: A REMOTE-CONTROLED MORTUARY ROBOT

BY:

OCHUDANG THOMAS AMAKE Reg.No: BU/UP/2016/260

Email: <a href="mailto:thomasamake@gmail.com">thomasamake@gmail.com</a>

Tel: +256779527319/ +256701601829

Supervisor: Mr. LUSIBA BADRU

A project Report submitted to the Department of Computer Engineering in Partial Fulfillment of the Requirement for the Award of a Bachelor's Degree in Computer Engineering of Busitema University

December,2020

#### **ABSTRACT**

In Uganda and worldwide, currently the cleaning and the embalming process of the dead bodies is done majorly using human labor known as mortuary attendants who are prone to the high risks of infections inside the mortuaries. And yet mortuaries are important integral in hospital which helps for storage of un identified bodies, examination in the post mortem room or removal for autopsy.

Use of Personal Protective Equipment (PPE) is one the method the mortuary attendants use to protect themselves from infections while performing their tasks in the mortuary. However, this method is constrained by certain factors like improper use of the PPE, too much heat due to the time taken putting on the PPE while performing the tasks in the mortuaries and also some hospitals in Uganda luck the PPE for the mortuary attendants. And this is one of the reasons why most mortuary attendants are at a risk of infections in the mortuaries.

In this system, the remote is used to control the robot movement inside the mortuary and also control the manipulation of the arms in performing the cleaning, the carrying and the embalming process.

Key words: Remote, Robot, Mortuary, Mortuary Attendants, Arms, Arduino, embalming, corpse.

#### **DECLARATION**

I **OCHUDANG THOMAS AMAKE**, an undergraduate student of a Bachelor of Computer Engineering solemnly declare that this research is my original work that has been done and prepared by myself. It has not been previously or concurrently submitted for the award of any academic degree, diploma or certificate of Busitema University or any other university. The materials borrowed from other sources and included herein have been properly cited and acknowledged. All information in this document has been obtained and presented in accordance with academic rules and ethical standards of the Busitema University Senate.

SIGN: .	••••	• • •	• • • •	 • •	• •	• •	 ٠.	 •	 •	 • •	 •	 •	 •	
DATE:				 			 			 				

#### **APPROVAL**

This is to approve that this Final Year Project Report has been fully and consistently worked on and submitted to the Department of Computer Engineering under the supervision of the undersigned supervisor.

•

DATE: .....

Mr. LUSIBA BADIRU

Department of Computer Engineering

Faculty of Engineering

Busitema University

#### **DEDICATION**

I dedicate this project report to my dear cousin sister Mary Francis, my beloved mother Akumu Jenifer for the love and support they have provided to me throughout this project period. I also dedicate it to my project supervisor Mr. Lusiba Badru for his tremendous effort and guidance in relation to my project report, the courage, moral and support he offered to me during my research period may the almighty bless him.

#### **ACKNOWLEDGEMENT**

Above all, I thank God the almighty for the gift of life, wisdom and guidance for without Him, nothing would have happened and I wouldn't be able to accomplish my project stage.

I cannot express enough thanks to my supervisor for his continued support and encouragement: Mr. Lusiba Badru. I offer my sincere appreciation for the learning skills provided by my supervisor. Also, I acknowledge all the other lecturers who have always given me time for consultation regardless of whether they are my supervisors or not, thank you for the helping attitude. My completion of this project could not have been accomplished without the support of my classmates; Tinkamanyire Amon, Kyazze Walid and all the other colleagues, thank you for allowing me time away from you to research and write. You deserve a trip to Germany. Lastly, I thank my family members My little sisters Joan and Mary, my Mother Mis Jenifer and finally my little brother Joseph for their support and prayers. The countless times you provided me support will not be forgotten.

## LIST OF ACRONYMS

PPE Personal Protective Equipment

RIP Rest in Peace.

ppm parts per million

HBV hepatitis B virus

HCV hepatitis C virus

HIV Human immunodeficiency virus

UV Ultra violet

EVD Ebola Virus Disease

Tables of Figures	
Figure 1: shows Inside a mortuary	3
Figure 2: system design layout	15
Figure 3 Conceptual system design	
Figure 4 Dataflow Diagram	
Figure 5: Physical design	
Figure 6 Arduino UNO Programming board	21
Figure 7 Circuit Diagram	
Figure 8 the developed system	26
List of Tables	
2.2.3 Table 1 comparison table for existing systems	11

## **Table of Contents**

ABSTRACT	i
DECLARATION	ii
APPROVAL	iii
DEDICATION	iv
ACKNOWLEDGEMENT	v
LIST OF ACRONYMS	vi
Tables of Figures	vii
CHAPTER ONE	1
1.Introduction	1
1.1Background of study	1
1.1.1 Natural means of preservation	2
1.1.2 Artificial means of preservation	2
1.2 Problem statement	3
1.3 Objectives	3
1.3.1 Main objective	3
1.3.2 Specific Objectives	3
1.4 Significance of the study.	3
1.5 Scope	3
1.5.1 Geographical scope	3
1.5.2 Technical scope	3
CHAPTER TWO	4
2.Literature Review	4
2.1 introduction	4
2.1.0 Definition of the system mortuary.	4
2.1.1 Autopsy or post-mortem	4
2.1.2 Mortuary attendant	4
2.3 Care of the Body After Death	5
2.3.2 Embalming	6
2.3.2.1 Natural means of preservation	7
2.3.2.2 Artificial means of preservation	7
2.3.2.1 Health effects of embalming products	10

2.4 Related work	10
2.2.1 Manual Process	10
2.2.3 Nursing-care Assistant Robot – Riba	10
2.2.4 surgery robot assistant	11
2.4.2 Developed system	11
3.Nursing-care Assistant Robot – Riba	12
5.Surgery robot assistant	12
CHAPTER THREE	13
3.0 METHODOLOGY	13
3.1 Introduction	13
3.2 Requirements Gathering	13
3.2.1 Literature review	13
3.1.3 Consultations:	13
3.1.3 Observation	13
3.3 Requirements analysis	13
3.4 System Design	13
3.4.1 Arduino ATmega328P microcontroller:	14
3.4.2 12V DC Battery:	14
3.4.3 Dc Motor and Motor Drivers	14
3.4.4 Servomotor	14
3.4.5 IR Remote/sender and Receiver	14
3.4.6 Arduino platform	14
3.4.8 System block diagram	15
3.4.9 Conceptual system design	16
CHAPTER FOUR: SYSTEM ANALYSIS AND DESIGN	17
4.0 Introduction	17
4.1 Functional Analysis	17
4.2 Requirement Analysis	17
4.2.1 Functional Requirements	17
4.2.2 Non-Functional Requirements	17
4.3 System design.	18
4.4 Data flow model	18

4.5 Logical and Physical design of the system.	19
CHAPTER FIVE: SYSTEM IMPLEMENTATION AND DESIGN	20
5.0 Introduction	20
5.1 Development Platforms	20
5.1.1 Arduino	20
5.1.2 Arduino Uno Microcontroller	20
5.2 Code Design	21
5.2.1 Robot locomotion Codes	21
5.3 Testing.	23
5.3.1 Unit testing.	23
5.3.2 Integration testing.	23
5.3.3 System testing.	23
5.4 System verification.	23
5.5 System validation	23
5.6 System evaluation.	23
CHAPTER SIX: DISCUSSION AND RECOMMENDATIONS	24
6.0 Introduction	24
6.1 Summary of the work	24
6.2 Critical analysis /appraisal of the work	24
6.3 Recommendations	24
6.4 Conclusion	24
References	25
APPENDIX	26
6.5 Circuit diagram	26
6.6 Physical design	26
6.7 Code design	27